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# On Poisson signal estimation under Kullback-Leibler discrepancy and squared risk 

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#### Abstract

Regression problems under Poisson variability arise in many different scientific areas such as, for examples, astrophysics and medical imaging. This article considers the problem of bandwidth selection for kernel smoothing of Poisson data. Its first contribution is the proposal of a new bandwidth selection method that aims to choose the bandwidth that minimizes the Kullback-Leibler (KL) distance between the estimated and the unknown true regression functions. The idea behind is to first construct an estimator of the KL distance and then chooses the minimizer of this distance estimator as the bandwidth. The consistency of this distance estimator is established. As a second contribution, this article establishes the consistency of an existing estimator that targets the $L_{2}$ risk between the true and the estimated regression functions. In a simulation study, when the targeting distance measure is the KL discrepancy, the proposed KL-based bandwidth selector outperforms a bandwidth selector that uses deviance cross-validation.


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## 1. Introduction

This article is concerned with regression function estimation under the following Poisson setting. Suppose $n$ independent Poisson counts $y_{j}$ are observed at a set of grid points $x_{j}$ :

$$
\begin{equation*}
y_{j} \sim P\left(f_{j}\right), \quad f_{j}=f\left(x_{j}\right), \quad x_{j}=\frac{j}{n}, \quad j=0, \ldots, n-1, \tag{1}
\end{equation*}
$$

where $P\left(f_{j}\right)$ denotes a Poisson distribution with mean $f_{j}$. The goal is to estimate the unknown regression function $f$, which is assumed to be "smooth". Practical applications covered by this setting include the estimation of X-ray or $\gamma$-ray burst intensity maps in astrophysics (e.g., Kolaczyk, 1997; van Dyk et al., 2001) and the smoothing of Poisson count data in medical imaging (e.g., Hudson and Lee, 1998; La Riviere and Pan, 2000). Possible generalizations to this setting, including non-equally spaced designs, will be discussed in Section 4.

For simplicity we shall primarily focus on the following kernel-smoothed estimator for $f$. Let $K$ be a kernel function. Let also $h$ be a non-negative smoothing parameter, also known as the bandwidth, that controls the amount of smoothing. Write $K_{h}(\cdot)=1 / h K(\cdot / h)$. The kernel estimator $\hat{f}_{j}$ for $f_{j}$ is defined as

$$
\begin{equation*}
\hat{f}_{j}=\frac{\sum_{m=0}^{n-1} K_{h}\left(x_{m}-x_{j}\right) y_{m}}{\sum_{l=0}^{n-1} K_{h}\left(x_{l}-x_{j}\right)}, \quad j=0, \ldots, n-1 \tag{2}
\end{equation*}
$$

Note that $\hat{f}_{j}$ is a function of $h$, but, for brevity, this dependence is suppressed from its notation. It is well known that the choice of $h$ is much more crucial than the choice of $K$ (e.g., see Wand and Jones, 1995).

The purpose of this article is to study, both theoretically and empirically, the properties of two data-dependent methods for choosing $h$. The first method aims to choose the $h$ that minimizes the following Kullback-Leibler (KL) discrepancy between $\hat{f}$ and $f$

$$
\begin{equation*}
\Delta_{\mathrm{KL}}(\hat{f}, f)=\frac{1}{n} \sum_{j=0}^{n-1}\left\{f_{j}-\hat{f}_{j}+\hat{f}_{j}\left(\log \hat{f}_{j}-\log f_{j}\right)\right\} \tag{3}
\end{equation*}
$$

Derivation for $\Delta_{\mathrm{KL}}(\hat{f}, f)$ is given in Appendix A. The second method aims for minimizing the $L_{2}$ risk between $\hat{f}$ and $f$

$$
\Delta_{\mathrm{R}}(\hat{f}, f)=\frac{1}{n} \sum_{j=0}^{n-1}\left(f_{j}-\hat{f}_{j}\right)^{2}
$$

Notice that both $\Delta_{\mathrm{KL}}(\hat{f}, f)$ and $\Delta_{\mathrm{R}}(\hat{f}, f)$ are unknown, therefore direct minimization of these two discrepancy measures is not possible. A common approach to overcoming this problem is first to construct an estimator for the discrepancy measure of interest, and then choose the bandwidth that minimizes such a discrepancy estimator. As mentioned in Linhart and Zucchini (1986), the rationale is that the bandwidth that minimizes the discrepancy estimator should also approximately minimize the unknown discrepancy. Other classical
statistical model selection criteria that follow this rationale include Mallows' $C_{p}$ and Akaike information criterion. This article proposes a consistent estimator for $\Delta_{\mathrm{KL}}(\hat{f}, f)$, as well as establishes the consistency of an existing estimator for $\Delta_{\mathrm{R}}(\hat{f}, f)$. It is worth mentioning that a technical challenge for estimating $\Delta_{\mathrm{KL}}(\hat{f}, f)$ occurs when $f_{j}$ is close to zero; i.e., when $\log f_{j}$ approaches $-\infty$.

The problem of function estimation under Poisson noise has of course been studied by various authors. Earlier references include Hudson $(1978,1985)$, who studied the problem from a $L_{2}$ perspective. Pawitan and O'Sullivan (1993) develop an $L_{2}$ risk-based method for choosing the amount of smoothing in medical image reconstruction. In the context of generalized linear models, a computational procedure, based on cross-validating (CV) the deviance, is described in Hastie and Tibshirani (1990, Chapter 6). Xiang and Wahba (1996) propose a generalized approximate cross-validation (GACV) procedure for choosing the smoothing parameter for smoothing splines with non-Gaussian data (see also Gu and Xiang, 2001). Their numerical results suggest that, in the Bernoulli noise case, GACV can be used to estimate the KL discrepancy. However, no proof has been provided for supporting this observation. Further results concerning the use of smoothing splines for non-Gaussian data can be found in Gu (2002, Chapter 5). More recently, a wavelet thresholding method tailored for Poisson noise is proposed by Kolaczyk (1998). Also, Kolaczyk (1999) and Nowak and Kolaczyk (2000) provide Bayesian multi-scale methods for handling Poisson inverse problems.

The rest of this article is organized as follows. The main theoretical contributions of this article are presented in Section 2. In Section 3, results from numerical experiments are reported for evaluating the two bandwidth selection methods mentioned above. Generalizations and conclusions are offered in Section 4. Technical details are deferred to the appendices.

## 2. Theoretical results

This section presents the main contributions of this article, namely, the proposal of a new consistent estimator for $\Delta_{\mathrm{KL}}(\hat{f}, f)$, and a theoretical study of an earlier estimator for $\Delta_{\mathrm{R}}(\hat{f}, f)$. We remark that the kernel estimator $\hat{f}_{j}$ can also be interpreted as a weighted average of the $y_{j}$ 's. It is because one could write

$$
\begin{equation*}
\hat{f}_{j}=\sum_{m} w_{m-j} y_{m} \quad \text { with } w_{m-j}=\frac{K_{h}\left(x_{m}-x_{j}\right)}{\sum_{l} K_{h}\left(x_{l}-x_{j}\right)} \tag{4}
\end{equation*}
$$

Notice that the weights $w_{m}$ 's sum to unity. In what follows we will assume that $f$ satisfies the periodic boundary condition; i.e., $f_{j}=f_{j+n}=f_{j-n}$ for $j=0, \ldots, n-1$. This will allow us to have the weights $w_{m}$ independent of location.

### 2.1. Estimating the KL discrepancy

One major difficulty behind the construction of an estimator for $\Delta_{\mathrm{KL}}(\hat{f}, f)$ is the need for estimating $\log f_{j}$ when $f_{j}$ is close to zero. It is because under this situation $y_{j}$ will take
value 0 with probability close to $1-f_{j} \approx 1$ and 1 with probability close to $f_{j} \approx 0$. This will in turn give rise to "low count" data. The way that we handle this "low count" situation is to lump neighboring observations of $y_{j}$ (i.e., $y_{j \pm k}$ for small $k$ ) together so that the sum of these $y_{j}$ 's is large enough to be worked with. Thus in our estimator, denoted as $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$, there is one integer parameter $k$ that needs to be pre-specified. This parameter $k$ is used to control the amount of lumping. At the end of this subsection we will discuss the issue of how to pre-specify $k$. The details of the construction of our estimator $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$, together with additional comments on $k$, are given in Appendix B. Here we only describe the main idea behind this construction.

When estimating $\Delta_{\mathrm{KL}}(\hat{f}, f)$ we need to be able to estimate $\log f_{j}$ and $f_{j} \log f_{j}$. If $Y$ has Poisson $(\lambda)$ distribution the arguments in Appendix B show that

$$
\begin{align*}
& E\left\{\left(\log Y-\frac{1}{2 Y}\right) I_{\{Y>0\}}\right\} \approx \log \lambda  \tag{5}\\
& E(Y \log Y)-\frac{1}{2} \approx \lambda \log \lambda \tag{6}
\end{align*}
$$

where $I_{E}$ is the indicator function for event $E$. The approximation in (6) is uniformly good for all $\lambda$, which suggests estimating $\lambda \log \lambda$ with $Y \log Y-\frac{1}{2} I_{\{Y>0\}}$. This and the lumping idea described above lead directly to the definition of $\beta_{j}^{k}$ below. The approximation in (5) needs bias correction for small $\lambda$. The bias corrected version of the estimator of $\log \lambda$ is then used below for the definition of $\alpha_{j}^{k}$. The estimator $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$ is then derived from (3) by replacing of $\log f_{j}$ by its estimator $\alpha_{j}^{k}$ and $f_{j} \log f_{j}$ by $\beta_{j}^{k}$.

We now can state the exact form of our estimator $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$. Define

$$
\begin{aligned}
y_{j}^{k}= & \sum_{|m| \leqslant k} y_{j+m}, \quad f_{j}^{k}=\sum_{|m| \leqslant k} f_{j+m}, \\
\alpha_{j}^{k}= & \left\{\log \frac{y_{j}^{k}}{2 k+1}+\frac{0.5}{y_{j}^{k}}-\frac{1.36177}{\left(y_{j}^{k}\right)^{2}}+\frac{2.15204}{\left(y_{j}^{k}\right)^{3}}\right\} I_{\left\{y_{j}^{k}>0\right\}} \\
& -\{\log (2 k+1)+2.10898\} I_{\left\{y_{j}^{k}=0\right\}}
\end{aligned}
$$

and

$$
\beta_{j}^{k}=\frac{y_{j}^{k}}{2 k+1} \log \frac{y_{j}^{k}}{2 k+1}-\frac{1}{2(2 k+1)} I_{\left\{y_{j}^{k}>0\right\}} .
$$

Our estimator admits the following expression:

$$
\hat{\Delta}_{\mathrm{KL}}^{k}(h)=\frac{1}{n} \sum_{j=0}^{n-1}\left(y_{j}-\hat{f}_{j}+\hat{f}_{j} \log \hat{f}_{j}-\alpha_{j}^{k} \sum_{|m| \geqslant k} w_{m} y_{j+m}-\beta_{j}^{k} \sum_{|m| \leqslant k} w_{m}\right) .
$$

If the target discrepancy measure is $\Delta_{\mathrm{KL}}(\hat{f}, f)$, we propose to choose the bandwidth $h$ as the minimizer of $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$.

We have established the consistency of our estimator. The results are summarized in the following theorem. The proof is given in Appendix C.

Theorem 1. Suppose that $f$ is Lipschitz with constant $D$ and bounded away from 0 and $\infty$, and that the kernel $K$ is compact, symmetrical, unimodal and square-integrable. Then

$$
\begin{align*}
\left|E\left\{\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)\right\}\right| \leqslant & \frac{C_{1} M_{1}}{M_{2}(2 k+1)^{2}}+\frac{C_{2}}{M_{2} b(2 k+1)}+\frac{C_{3} M_{1} D k(k+1)}{M_{2}(2 k+1) n} \\
& +\frac{C_{4} D k(k+1)}{n b}\left\{1+2 \max \left(-\log M_{2}, \log M_{1}\right)\right\} \\
& +\frac{C_{5} D^{2} k^{2}(1+k)^{2}}{M_{1}(2 k+1) n^{2} b} \tag{7}
\end{align*}
$$

where $M_{1}=\max f(x), M_{2}=\min f(x), b$ is the number of $y_{j}$ 's in the support of $K_{h}$, and $C_{1}, C_{2}, C_{3}, C_{4}, C_{5}$ are constants depending only on $K$. Furthermore,

$$
\begin{equation*}
\operatorname{var}\left\{\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)\right\} \leqslant C \frac{b}{n}, \tag{8}
\end{equation*}
$$

where $C$ is a constant depending only on $f$.
In addition, if $k<b<n$ are simultaneously approaching infinity, $b=0\left\{\min \left(n^{1 / 3}, k^{2}\right)\right\}$, then

$$
\begin{equation*}
\frac{\hat{U}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)}{\Delta_{\mathrm{KL}}(\hat{f}, f)} \rightarrow 0 \quad \text { in probability. } \tag{9}
\end{equation*}
$$

We remark that the quantity $b$ plays a dual role to the bandwidth $h$. It is because $b=\lfloor L n h\rfloor$ if $L$ is the length of the support of $K$.

Now we consider the choice of $k$. Of course its optimal value would depend on different unknown quantities such as various properties of $f$. In practice these quantities may not be available, which makes pre-specifying the optimal value of $k$ difficult. However, from our numerical experience, setting $k=1$ is often a good and conservative choice. We have used $k=1$ through out all our numerical experiments described in Section 3 below.

Remark 1. The established consistency of the estimator $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$ suggests an important implication about the asymptotic behavior of our estimator. Denote $\hat{f}_{h_{\mathrm{KL}, 0}}$ the estimator of $f$ calculated using the optimal bandwidth $h_{\mathrm{KL}, 0}$ minimizing $\Delta_{\mathrm{KL}}(\hat{f}, f)$ (not obtainable
 $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$ (our estimator). Assume that

$$
\frac{\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)}{\Delta_{\mathrm{KL}}(\hat{f}, f)} \rightarrow 0
$$

for both $h=\hat{h}_{\mathrm{KL}}$ and $h=h_{\mathrm{KL}, 0}$. This could be achieved for example by strengthening equation (9) of Theorem 1 to hold uniformly for all $h$. Then

$$
\begin{equation*}
\frac{\hat{\Delta}_{\mathrm{KL}}^{k}\left(\hat{h}_{\mathrm{KL}}\right)}{\Delta_{\mathrm{KL}}\left(\hat{f}_{\hat{h}_{\mathrm{KL}}}, f\right)} \rightarrow 1 \quad \text { and } \quad \frac{\Delta_{\mathrm{KL}}\left(\hat{f}_{h_{\mathrm{KL}, 0}}, f\right)}{\hat{\Delta}_{\mathrm{KL}}^{k}\left(h_{\mathrm{KL}, 0}\right)} \rightarrow 1 \tag{10}
\end{equation*}
$$

Since $\hat{f}_{h_{\mathrm{KL}, 0}}$ minimizes $\Delta_{\mathrm{KL}}(\hat{f}, f)$ and $\hat{f}_{\hat{h}_{\mathrm{KL}}}$ minimizes $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$, we have

$$
\begin{equation*}
\frac{\Delta_{\mathrm{KL}}\left(\hat{f}_{\hat{h_{\mathrm{KL}}}}, f\right)}{\Delta_{\mathrm{KL}}\left(\hat{f}_{h_{\mathrm{KL}, 0}}, f\right)} \geqslant 1 \quad \text { and } \quad \frac{\hat{\Delta}_{\mathrm{KL}}^{k}\left(h_{\mathrm{KL}, 0}\right)}{\hat{\Delta}_{\mathrm{KL}}^{k}\left(\hat{h}_{\mathrm{KL}}\right)} \geqslant 1 . \tag{11}
\end{equation*}
$$

From here and (10) calculate

$$
\begin{equation*}
\limsup _{n \rightarrow \infty} \frac{\Delta_{\mathrm{KL}}\left(\hat{f}_{\hat{h}_{\mathrm{KL}}}, f\right)}{\Delta_{\mathrm{KL}}\left(\hat{f}_{h_{\mathrm{KL}, 0}}, f\right)} \leqslant \limsup _{n \rightarrow \infty} \frac{\Delta_{\mathrm{KL}}\left(\hat{f}_{\hat{h}_{\mathrm{KL}}}, f\right)}{\Delta_{\mathrm{KL}}\left(\hat{f}_{h_{\mathrm{KL}, 0}}, f\right)} \cdot \frac{\hat{\Delta}_{\mathrm{KL}}^{k}\left(h_{\mathrm{KL}, 0}\right)}{\hat{\Delta}_{\mathrm{KL}}^{k}\left(\hat{h}_{\mathrm{KL}}\right)}=1 . \tag{12}
\end{equation*}
$$

Combining (11) and (12) we have $\Delta_{\mathrm{KL}}\left(\hat{f}_{\hat{h}_{\mathrm{KL}}}, f\right) / \Delta_{\mathrm{KL}}\left({\hat{f_{h}}}_{\mathrm{KL}, 0}, f\right) \rightarrow 1$ concluding that $\Delta_{\mathrm{KL}}\left({\hat{f_{\hat{h}}^{\mathrm{KL}}}}, f\right)$ converges to 0 at the same speed as $\Delta_{\mathrm{KL}}\left(\hat{f}_{h_{\mathrm{KL}, 0}}, f\right)$.

### 2.2. Estimating the $L_{2}$ risk

Unbiased estimation of the $L_{2}$ risk under Poisson variability has been studied by previous authors; e.g., see Hudson (1978) and Pawitan and O'Sullivan (1993). For the current setting, the following estimator $\hat{\Delta}_{\mathrm{R}}(h)$ for $\Delta_{\mathrm{R}}(\hat{f}, f)$ can be obtained from results in Pawitan and O'Sullivan (1993):

$$
\hat{\Delta}_{\mathrm{R}}(h)=\frac{1}{n} \sum_{j}\left\{\left(y_{j}-\hat{f}_{j}\right)^{2}+\left(2 w_{0}-1\right) y_{j}\right\}
$$

One could choose $h$ as the minimizer of $\hat{\Delta}_{\mathrm{R}}(h)$ if $\Delta_{\mathrm{R}}(\hat{f}, f)$ is the target discrepancy measure.
We have also studied the theoretical properties of $\hat{\Delta}_{\mathrm{R}}(h)$ in a similar fashion as for $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$. Our results are summarized in the theorem below. In short, our contribution in this subsection is that we have established the consistency of $\hat{\Delta}_{\mathrm{R}}(h)$. Proof of the theorem is delayed to Appendix D.

Theorem 2. Suppose that fis Lipschitz and bounded, and that $K$ is compact, symmetrical, unimodal and square-integrable. Then

$$
\begin{equation*}
E\left\{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)\right\}=0 \tag{13}
\end{equation*}
$$

and

$$
\begin{equation*}
\operatorname{var}\left\{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)\right\} \leqslant C \frac{b}{n}, \tag{14}
\end{equation*}
$$

where $C$ is a constant depending only on $f$.
In addition, if $b=\mathrm{o}\left(n^{1 / 3}\right)$

$$
\begin{equation*}
\frac{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)}{\Delta_{\mathrm{R}}(\hat{f}, f)} \rightarrow 0 \quad \text { in probability. } \tag{15}
\end{equation*}
$$

### 2.3. Computational issues

Both of the above two bandwidth selection procedures are computationally inexpensive and straightforward to implement. It is because both $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$ and $\hat{\Delta}_{\mathrm{R}}(h)$ can be directly computed without using any Monte Carlo-type approximations. Also, since the data are assumed to be regularly spaced, fast computation of $\hat{f}_{j}$ can be achieved by using Fourier techniques.

## 3. Numerical results

A small-scale simulation study was conducted to evaluate the empirical properties of the two bandwidth selection methods discussed above. For comparative purposes, the CV deviance procedure described in Hastie and Tibshirani (1990, Chapter 6) was also studied. This procedure chooses the bandwidth $h$ that minimizes the following leave-one-out CV deviance function

$$
\operatorname{CVDev}(h)=\frac{1}{n} \sum_{j=0}^{n-1}\left\{\hat{f}_{-j}-y_{j}+y_{j}\left(\log y_{j}-\log \hat{f}_{-j}\right)\right\}
$$

where $\hat{f}_{-j}$ is the estimate of $f_{j}$ obtained from using all but the $i$ th observation $y_{i}$. Notice that $\operatorname{CVDev}(h)$ is targeting the KL discrepancy.

### 3.1. Setup

In this study three test functions, three signal-to-noise ratios (snrs) and four sample sizes were used. The three test functions were
Test Function 1: $f(x)=\max \{\sin (4 \pi x), \varepsilon\}, \quad \varepsilon=0.000005$,
Test Function 2: $\quad f(x)=\max \{\sin (4 \pi x)+1, \varepsilon\}$,
Test Function 3: $\quad f(x)=2 \sin (4 \pi x)+3$.
These three test functions are derived from a standard sine wave and present three different levels of difficulties. For Test Function 1 half of its domain "touches zero" (i.e., has " $y$ value" that are virtually zero), for Test Function 2 the valleys of the sine wave "touch zero", while for Test Function 3 the whole sine wave is shifted up so that it is sufficiently far away from zero. As indicated above a major difficulty for estimating $\Delta_{\mathrm{KL}}(\hat{f}, f)$ is the estimation


Fig. 1. Visual inspection for Test Function 1 with $n=200$. Top-left: true function (solid line) with noisy data points superimposed. Top-right: true function (solid line) with estimated function using $h=\hat{h}_{\mathrm{KL}}$ (broken line). Bottom-left: true function (solid line) with estimated function using $h=\hat{h}_{\mathrm{R}}$ (broken line). Bottom-right: true function (solid line) with estimated function using $h=\hat{h}_{\mathrm{DEV}}$ (broken line).
of $\log f(x)$ when $f(x) \approx 0$. Thus one may treat that Test Function 1 is a hard example, Test Function 2 is a medium example while Test Function 3 is an easy example. Plots of the test functions can be found in Figs. 1-6.

We define snr as $\|f\| / \sqrt{\operatorname{var}(f)}=\sqrt{\sum f_{j}^{2} / \sum f_{j}}$, where $\operatorname{var}(f)$ can be interpreted as the variance of the noise. To change the snr of a test function $f$, a constant $c$ is multiplied to it so that $\sqrt{\sum\left(c f_{j}\right)^{2} / \sum c f_{j}}$ reaches the pre-specified value. The three snrs used were 2,4 , and 6 . The four sample sizes were $n=200,400,800$ and 1600. The kernel function used was $K(x)=\frac{3}{4}\left(1-x^{2}\right), x \in[0,1]$. It is the optimal kernel of order $(0,2)$ derived in Gasser et al. (1985). Throughout the whole study we set $k=1$.

For each of the above 36 experimental settings, 250 independent data sets were simulated. For each of these simulated data sets, the bandwidths $\hat{h}_{\mathrm{KL}}, \hat{h}_{\mathrm{R}}$ and $\hat{h}_{\mathrm{DEV}}$ that minimize, respectively, $\left.\hat{\Delta}_{\mathrm{KL}}^{k}(h)\right|_{k=1}, \hat{\Delta}_{\mathrm{R}}(h)$ and $\operatorname{CVDev}(h)$ were computed. In addition, two practically unobtainable optimal bandwidths were also computed. They were $h_{\mathrm{KL}, 0}$, the bandwidth that minimizes $\Delta_{\mathrm{KL}}(\hat{f}, f)$, and $h_{\mathrm{R}, 0}$, the bandwidth that minimizes $\Delta_{\mathrm{R}}(\hat{f}, f)$.


Fig. 2. Similar to Fig. 1 but for Test Function 1 with $n=800$.

### 3.2. Results

Four numerical measures were adopted to evaluate the quality of $\hat{h}_{\mathrm{KL}}$. Let $\hat{f}_{[h]}$ be the estimate of $f$ computed using the bandwidth $h$. The four numerical measures were

$$
\Delta_{\mathrm{KL}}\left(\hat{f}_{\left[\hat{h}_{\mathrm{KL}}\right]}, f\right), \quad \Delta_{\mathrm{R}}\left(\hat{f}_{\left[\hat{h}_{\mathrm{KL}}\right]}, f\right), \quad \frac{\Delta_{\mathrm{KL}}\left(\hat{f}_{\left[\hat{h}_{\mathrm{KL}}\right]}, f\right)}{\Delta_{\mathrm{KL}}\left(\hat{f}_{\left[h_{\mathrm{KL}, 0}\right]}, f\right)} \quad \text { and } \quad \frac{\Delta_{\mathrm{R}}\left(\hat{f}_{\left[\hat{h}_{\mathrm{KL}}\right]}, f\right)}{\Delta_{\mathrm{R}}\left(\hat{f}_{\left[h_{\mathrm{R}, 0}\right]}, f\right)} .
$$

The first and the third measures were used to assess the performance of $\hat{h}_{\mathrm{KL}}$ when $\Delta_{\mathrm{KL}}(\hat{f}, f)$ is of interest: the first assesses the quality in an absolute sense while the third assesses the quality relative to the best possible bandwidth $h_{\mathrm{KL}, 0}$ that one could get only if $f$ is known. Although $\hat{h}_{\mathrm{KL}}$ is not targeting the $L_{2}$ risk $\hat{\Delta}_{\mathrm{R}}(h)$, it would still be interesting and worthwhile to include the second and the fourth measures. Averages and standard deviations for these four measures, computed from the 250 repetitions for each experiment setting, are given in Tables 1-4. Similar values for evaluating the quality of $\hat{h}_{\mathrm{R}}$ and $\hat{h}_{\text {DEV }}$ were also computed and are reported in the same tables.

The following empirical conclusions can be drawn from examining these tables. First, for all experimental settings, the values of $\Delta_{\mathrm{KL}}(\hat{f}, f)$ and $\Delta_{\mathrm{R}}(\hat{f}, f)$ decrease as $n$ increases


Fig. 3. Similar to Fig. 1 but for Test Function 2 with $n=200$.
(see Tables 1 and 2). Secondly, for the "easy" Test Function 3, all three bandwidth selectors $\hat{h}_{\mathrm{KL}}, \hat{h}_{\mathrm{R}}$ and $\hat{h}_{\mathrm{DEV}}$ gave very similar performances regardless of which numerical measure is being used. Thirdly, for Test Functions 1 and $2, \hat{h}_{\mathrm{KL}}$ seems to outperform $\hat{h}_{\mathrm{DEV}}$ when the targeting distance measure is the KL discrepancy. Lastly, as most of the corresponding entries in Table 3 are close to 1 , the proposed $\hat{h}_{\mathrm{KL}}$ gave very good results when comparing to the best possible (but practically unobtainable) $h_{\mathrm{KL}, 0}$.

To visually evaluate the quality of various estimated curves, the following was done. For Test Function 1 with $\mathrm{snr}=4$ and $n=200$, the simulated data set that corresponds to the 125th sorted value of $\Delta_{\mathrm{KL}}\left(\hat{f}_{\left[\hat{h}_{\mathrm{KL}}\right]}, f\right)$ is plotted in Fig. 1, together with the estimated curves computed using the corresponding $\hat{h}_{\mathrm{KL}}, \hat{h}_{\mathrm{R}}$ and $\hat{h}_{\mathrm{DEV}}$. Similar plots were also produced for $n=800$ and also for Test Functions 2 and 3; they are displayed in Figs. 2-6.

## 4. Concluding remarks

In this article the problem of bandwidth selection for kernel regression with Poisson data is considered. A new bandwidth selection procedure that targets the KL discrepancy is proposed and both analytically and empirically studied. In addition, an existing $L_{2}$ riskbased bandwidth selection procedure is also studied. In a simulation study the proposed


Fig. 4. Similar to Fig. 1 but for Test Function 2 with $n=800$.
bandwidth selection procedure out-performed a deviance cross-validation-based procedure if the KL discrepancy is the target distance measure.

Several important extensions of this work are worth considering. The first one comes when the design points are non-equally spaced. One can construct an estimator for the KL discrepancy as before, but use nearest neighbors when calculating $y_{j}^{k}$. This approach works well if the design points $x$ are dense enough. For example if $\max _{j}\left(x_{j}-x_{j-1}\right) \rightarrow 0$ then the theorems of this article can be straightforwardly modified to show that the resulting estimator is consistent.
Another direct extension is to apply the above methodology to the class of linear nonparametric smoothing estimators that produce estimates $\hat{\boldsymbol{f}}$ of the form $\hat{\boldsymbol{f}}=\boldsymbol{H y}$, where $\boldsymbol{y}=$ $\left(y_{0}, \ldots, y_{n-1}\right)^{\mathrm{T}}$ and $\boldsymbol{H}$ is known as the "hat" or the "smoother" matrix. The kernel estimator considered in this article is a member of this class. Other class members include smoothing splines and penalized regression splines.

Extension to two-dimensional regularly spaced data setting (e.g., image data) is straightforward. Another possible extension of this work we are currently investigating is to construct similar KL discrepancy estimators for the use in generalized linear and additive models.

Table 1
Averages and standard deviations (in parentheses) of $\Delta_{\mathrm{KL}}\left(\hat{f}_{[h]}, f\right)$ for $h=\hat{h}_{\mathrm{KL}}\left(\right.$ minimizer of $\left.\hat{\Delta}_{\mathrm{KL}}^{k}(h)\right), h=\hat{h}_{\mathrm{R}}$ (minimizer of $\left.\hat{\Delta}_{\mathrm{R}}(h)\right)$ and $h=\hat{h}_{\mathrm{DEV}}($ minimizer of $\operatorname{CVDev}(h)$ )

| Test <br> Function | Bandwidth <br> selection | Sample size |  |  |  |  |  | $n=800$ | $n=1600$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | $\hat{h}_{\text {KL }}$ | $0.284(0.005)$ | $0.150(0.002)$ | $0.088(0.001)$ | $0.051(0.001)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $0.927(0.021)$ | $0.598(0.014)$ | $0.404(0.010)$ | $0.277(0.006)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ | $0.333(0.008)$ | $0.181(0.004)$ | $0.104(0.002)$ | $0.060(0.001)$ |  |  |  |  |
| 2 | $\hat{h}_{\mathrm{KL}}$ | $0.081(0.001)$ | $0.043(0.001)$ | $0.025(0.001)$ | $0.015(0.001)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $0.153(0.004)$ | $0.090(0.002)$ | $0.056(0.001)$ | $0.034(0.001)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ | $0.087(0.002)$ | $0.047(0.001)$ | $0.026(0.001)$ | $0.015(0.001)$ |  |  |  |  |
| 3 | $\hat{h}_{\mathrm{KL}}$ | $0.037(0.001)$ | $0.020(0.001)$ | $0.012(0.001)$ | $0.007(0.001)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $0.037(0.001)$ | $0.020(0.001)$ | $0.012(0.001)$ | $0.007(0.001)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ | $0.037(0.001)$ | $0.020(0.001)$ | $0.012(0.001)$ | $0.006(0.001)$ |  |  |  |  |

Table 2
Similar to Table 1 but for $\Delta_{\mathrm{R}}\left(f, \hat{f}_{[h]}\right)$

| Test <br> Function | Bandwidth selection | Sample size |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $n=200$ | $n=400$ | $n=800$ | $n=1600$ |
| 1 | $\hat{h}_{\text {KL }}$ | 1.175 (0.027) | 0.754 (0.015) | 0.486 (0.009) | 0.321 (0.006) |
|  | $\hat{h}^{\text {R }}$ | 0.814 (0.022) | 0.465 (0.011) | 0.270 (0.006) | 0.165 (0.004) |
|  | $\hat{h}_{\text {DEV }}$ | 1.164 (0.034) | 0.708 (0.018) | 0.444 (0.009) | 0.292 (0.006) |
| 2 | $\hat{h}_{\mathrm{KL}}$ | 1.066 (0.027) | 0.588 (0.014) | 0.345 (0.008) | 0.204 (0.004) |
|  | $\hat{h}_{\text {R }}$ | 0.876 (0.027) | 0.428 (0.011) | 0.253 (0.006) | 0.147 (0.003) |
|  | $\hat{h}_{\text {DEV }}$ | 0.991 (0.027) | 0.524 (0.012) | 0.317 (0.007) | 0.194 (0.004) |
| 3 | $\hat{h}_{\mathrm{KL}}$ | 0.892 (0.026) | 0.499 (0.013) | 0.297 (0.008) | 0.164 (0.004) |
|  | $\hat{h}_{\text {R }}$ | 0.889 (0.026) | 0.495 (0.014) | 0.284 (0.007) | 0.158 (0.004) |
|  | $\hat{h}_{\text {DEV }}$ | 0.905 (0.026) | 0.490 (0.013) | 0.290 (0.007) | 0.16 (0.004) |

Table 3
Similar to Table 1 but for $\Delta_{\mathrm{KL}}\left(\hat{f}_{[h]}, f\right) / \Delta_{\mathrm{KL}}\left(\hat{f}_{\left[h_{\mathrm{KL}, 0}\right]}, f\right)$

| Test <br> Function | Bandwidth <br> selection | Sample size |  |  |  |  | $n=400$ | $n=800$ | $n=1600$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | $n=200$ | $1.835(0.031)$ | $1.641(0.023)$ | $1.584(0.021)$ | $1.541(0.023)$ |  |  |  |  |
| 1 | $\hat{h}_{\text {KL }}$ | $6.299(0.196)$ | $6.827(0.198)$ | $7.584(0.217)$ | $8.539(0.223)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $2.147(0.051)$ | $2.001(0.044)$ | $1.874(0.034)$ | $1.821(0.036)$ |  |  |  |  |
| 2 | $\hat{h}_{\text {DEV }}$ | $1.118(0.009)$ | $1.096(0.008)$ | $1.096(0.008)$ | $1.085(0.008)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{KL}}$ | $2.260(0.067)$ | $2.399(0.063)$ | $2.540(0.066)$ | $2.614(0.071)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $1.213(0.017)$ | $1.180(0.013)$ | $1.136(0.010)$ | $1.112(0.008)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ | $1.159(0.018)$ | $1.155(0.017)$ | $1.162(0.017)$ | $1.121(0.013)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{KL}}$ | $1.169(0.018)$ | $1.170(0.019)$ | $1.136(0.014)$ | $1.116(0.009)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $1.187(0.022)$ | $1.145(0.017)$ | $1.142(0.015)$ | $1.100(0.010)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ |  |  |  |  |  |  |  |  |



Fig. 5. Similar to Fig. 1 but for Test Function 3 with $n=200$.

Table 4
Similar to Table 1 but for $\Delta_{\mathrm{R}}\left(f, \hat{f}_{[h]}\right) / \Delta_{\mathrm{R}}\left(f, \hat{f}_{\left[h_{\mathrm{R}, 0}\right]}\right)$

| Test <br> Function | Bandwidth <br> selection | Sample size |  |  |  |  |  | $n=800$ | $n=1600$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :---: | :---: | :---: | :---: |
|  | $\hat{h}_{\mathrm{KL}}$ | $1.759(0.033)$ | $1.985(0.043)$ | $2.149(0.041)$ | $2.269(0.045)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $1.206(0.031)$ | $1.193(0.029)$ | $1.144(0.015)$ | $1.117(0.012)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ | $1.746(0.051)$ | $1.863(0.053)$ | $1.954(0.043)$ | $2.053(0.042)$ |  |  |  |  |
| 2 | $\hat{h}_{\mathrm{KL}}$ | $1.597(0.041)$ | $1.698(0.037)$ | $1.602(0.032)$ | $1.585(0.028)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $1.249(0.032)$ | $1.182(0.021)$ | $1.137(0.017)$ | $1.113(0.014)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ | $1.458(0.036)$ | $1.497(0.030)$ | $1.471(0.027)$ | $1.507(0.025)$ |  |  |  |  |
| 3 | $\hat{h}_{\mathrm{KL}}$ | $1.198(0.022)$ | $1.197(0.021)$ | $1.204(0.020)$ | $1.157(0.016)$ |  |  |  |  |
|  | $\hat{h}_{\mathrm{R}}$ | $1.190(0.021)$ | $1.184(0.021)$ | $1.147(0.017)$ | $1.111(0.012)$ |  |  |  |  |
|  | $\hat{h}_{\text {DEV }}$ | $1.232(0.028)$ | $1.170(0.019)$ | $1.174(0.019)$ | $1.120(0.012)$ |  |  |  |  |

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Fig. 6. Similar to Fig. 1 but for Test Function 3 with $n=800$.

## Appendix A. Derivation of $\Delta_{\mathrm{KL}}(\hat{f}, f)$

The KL discrepancy for measuring the distance between two discrete probability density functions (pdfs) $g_{1}(t)$ and $g_{2}(t)$ is defined as

$$
d\left(g_{1}, g_{2}\right)=\sum_{t} g_{1}(t) \log \frac{g_{1}(t)}{g_{2}(t)}
$$

(e.g., see Burnham and Anderson, 1998). Note that $d\left(g_{1}, g_{2}\right) \neq d\left(g_{2}, g_{1}\right)$. For the current problem, in order to use $d\left(g_{1}, g_{2}\right)$ for comparing a true $f$ and an estimate $\hat{f}$, one needs to compare them design point by design point. At design point $x_{j}$, the pdf $g_{f}(t)$ corresponding to $f$ is Poisson with mean $f_{j}$. That is, $g_{f}(t)=\mathrm{e}^{-f_{j}} f_{j}^{t} / t!, t=0,1, \ldots$. For $\hat{f}$, a natural candidate for the corresponding pdf is Poisson with mean $\hat{f}_{j}$. Denote this pdf as $g_{\hat{f}}(t)$, and thus $g_{\hat{f}}(t)=\mathrm{e}^{-\hat{f}_{j}} \hat{f}_{j}^{t} / t!, t=0,1, \ldots$. We choose to measure the distance between $f$ and $\hat{f}$
at $x_{j}$ with

$$
\begin{aligned}
d\left(g_{\hat{f}}, g_{f}\right) & =\sum_{t=0}^{\infty} g_{\hat{f}}(t) \log \frac{g_{\hat{f}}(t)}{g_{f}(t)}=\sum_{t=0}^{\infty} \frac{\mathrm{e}^{-\hat{f}_{j}} \hat{f}_{j}^{t}}{t!} \log \frac{\mathrm{e}^{-\hat{f}_{j}} \hat{f}_{j}^{t} / t!}{\mathrm{e}^{-f_{j}} f_{j}^{t} / t!} \\
& =f_{j}-\hat{f}_{j}+\hat{f}_{j}\left(\log \hat{f}_{j}-\log f_{j}\right)
\end{aligned}
$$

Upon summing over $j$ we obtain $\Delta_{\mathrm{KL}}(\hat{f}, f)$.
Notice that one could also use $\Delta_{\mathrm{KL}}(f, \hat{f})$ (i.e., use $\left.d\left(g_{f}, g_{\hat{f}}\right)\right)$ instead of $\Delta_{\mathrm{KL}}(\hat{f}, f)$ (i.e., use $d\left(g_{\hat{f}}, g_{f}\right)$ ), but we choose $\Delta_{\mathrm{KL}}(\hat{f}, f)$ for the following reason. Using the Taylor series approximation $1-y+y \log y=(y-1)^{2} / 2$ for $y \approx 1$, we obtain

$$
\Delta_{\mathrm{KL}}(\hat{f}, f) \approx \frac{1}{2 n} \sum_{j=0}^{n-1} \frac{\left(f_{j}-\hat{f}_{j}\right)^{2}}{f_{j}}
$$

and

$$
\Delta_{\mathrm{KL}}(f, \hat{f})=\frac{1}{n} \sum_{j=0}^{n-1}\left\{\hat{f}_{j}-f_{j}+f_{j}\left(\log f_{j}-\log \hat{f}_{j}\right)\right\} \approx \frac{1}{2 n} \sum_{j=0}^{n-1} \frac{\left(f_{j}-\hat{f}_{j}\right)^{2}}{\hat{f}_{j}}
$$

Our belief is that $\Delta_{\mathrm{KL}}(\hat{f}, f)$ is a better measure to use, as in the above approximation it uses a fixed quantity, the denominator term $f_{j}$, to adjust for the variance of $\left(f_{j}-\hat{f}_{j}\right)^{2}$ while $\Delta_{\mathrm{KL}}(f, \hat{f})$ uses a random quantity $\hat{f_{j}}$. In addition, for the following reason $\Delta_{\mathrm{KL}}(\hat{f}, f)$ is more desirable in the case when $f_{j} \approx 0$ for several consecutive $j$ 's. In this case it is quite possible that $\hat{f}_{j}=0$ for some small values of bandwidth $h$, which causes $\Delta_{\mathrm{KL}}\left(g_{f_{j}}, g_{\hat{f}_{j}}\right)=\infty$ while $\Delta_{\mathrm{KL}}\left(g_{\hat{f}_{j}}, g_{f_{j}}\right)=f_{j}$, and of course the latter is more reasonable. Thus in order to get a finite $\Delta_{\mathrm{KL}}\left(g_{f_{j}}, g_{\hat{f}_{j}}\right)$ and hence finite $\Delta_{\mathrm{KL}}(f, \hat{f})$ the bandwidth will have to be large enough to guarantee $\hat{f}_{j}>0$. This may possibly lead to oversmoothing in other parts of $f$. On the other hand $\Delta_{\mathrm{KL}}(\hat{f}, f)$ does not suffer from this issue.

## Appendix B. Construction of $\hat{\Delta}_{\mathrm{KL}}^{k}(\boldsymbol{h})$

This appendix outlines the construction of $\hat{\Delta}_{h, k}$. The goal is to find an unbiased estimator of $\Delta_{\mathrm{KL}}(\hat{f}, f)$, which breaks down to the estimation of $f_{j}$ and $\hat{f}_{j} \log f_{j}$. Estimation of $f_{j}$ is straightforward as $E\left(y_{j}\right)=f_{j}$. As shown below, the estimation of $\hat{f}_{j} \log f_{j}$ can be further broken down to the estimation of $\log f_{j}$ and $f_{j} \log f_{j}$. However, this poses a bigger challenge as $\log f_{j} \approx-\infty$ whenever $f_{j} \approx 0$. We first work on $\log f_{j}$.

Here and in what follows let $Y$ denote a Poisson $(\lambda)$ random variable. Consider estimating $\log \lambda$ (i.e., $\log f_{j}$ ). The Taylor's series expansion of $\log y$ at the point $\lambda$ is
$\log y \approx \log \lambda+(y-\lambda) / \lambda-(y-\lambda)^{2} /\left(2 \lambda^{2}\right)$, which leads to

$$
\begin{equation*}
E\left\{(\log Y) I_{\{Y>0\}}\right\} \approx \log \lambda-\frac{1}{2 \lambda} \tag{16}
\end{equation*}
$$

This suggests estimating $\log \lambda$ by

$$
\begin{equation*}
\{\log Y-1 /(2 Y)\} I_{\{Y>0\}} \tag{17}
\end{equation*}
$$

where the factor of $1 /(2 Y)$ is motivated by the fact that $E\left\{(2 Y)^{-1} I_{\{Y>0\}}\right\} \approx 1 /(2 \lambda)$. The approximation in (16) works very well for large $\lambda$. However, the bias is not satisfactory for $\lambda<10$. To correct this we suggest the following correction. Take an estimator

$$
\begin{equation*}
G=C_{0} I_{\{Y=0\}}+\left\{\log Y-\frac{1}{2 Y}+\frac{C_{1}}{Y^{2}}+\frac{C_{2}}{Y^{3}}\right\} I_{\{Y>0\}} \tag{18}
\end{equation*}
$$

and choose $C_{0}, C_{1}$ and $C_{2}$ to minimize $\int_{1}^{\infty}\{E(G)-\log \lambda\}^{2} \mathrm{~d} \lambda$, where $E(G)$ is considered as a function of $\lambda$. The motivation of this step is that the effect of the added terms is negligible for large values of $\lambda$. More precisely it is of the order $\mathrm{O}\left(1 / \lambda^{2}\right)$. At the same time the choice of $C_{0}, C_{1}$ and $C_{2}$ will guarantee improvement of the bias for small values of $\lambda$. We performed numerical integration and obtain $C_{0}=2.10898, C_{1}=1.36177$ and $C_{2}=2.15204$. These constants improved the bias remarkably for $\lambda>1$.

Recall that a major difficulty with estimating $\log f_{j}$ occurs when $f_{j}$ is close to zero. To overcome this difficulty, we make use of the fact that if $f$ is locally smooth, then $f_{j-k} \approx$ $\ldots \approx f_{j+k}$ for small $k$. This implies that $y_{j-k}, \ldots, y_{j+k}$ are approximately independent and identically distributed as Poisson with mean $f_{j}$. Therefore $y_{j}^{k}=\sum_{m=-k}^{k} y_{j+m}$ has approximately Poisson distribution with mean $\lambda=(2 k+1) f_{j}$. Now if $k$ is large enough so that $\lambda>1$, we have

$$
\begin{equation*}
E(G) \approx \log f_{j}+\log (2 k+1) \tag{19}
\end{equation*}
$$

Thus combining (18) and (19) we derive the estimator of $\log f_{j}$ as

$$
\begin{aligned}
\alpha_{j}^{k}= & \left\{\log \frac{y_{j}^{k}}{2 k+1}+\frac{1}{2 y_{j}^{k}}-\frac{1.36177}{\left(y_{j}^{k}\right)^{2}}+\frac{2.15204}{\left(y_{j}^{k}\right)^{3}}\right\} I_{\left\{y_{j}^{k}>0\right\}} \\
& -\{\log (2 k+1)+2.10898\} I_{\left\{y_{j}^{k}=0\right\}}
\end{aligned}
$$

Now we consider estimating $\lambda \log \lambda\left(\right.$ or $\left.f_{j} \log f_{j}\right)$. The Taylor's series expansion of $y \log y$ at the point $\lambda$ is $y \log y \approx \lambda \log \lambda+(y-\lambda)(1+\log \lambda)+(y-\lambda)^{2} /(2 \lambda)$, which gives

$$
\begin{equation*}
E(Y \log Y) \approx \lambda \log \lambda+\frac{1}{2} \tag{20}
\end{equation*}
$$

Similarly as before we plug $y_{j}^{k}$ into (20) and obtain

$$
y_{j}^{k} \log y_{j}^{k}-\frac{1}{2} I_{\left\{y_{j}^{k}>0\right\}} \approx(2 k+1)\left\{f_{j} \log f_{j}-f_{j} \log (2 k+1)\right\},
$$

which leads to

$$
\beta_{j}^{k}=\frac{y_{j}^{k}}{2 k+1} \log \frac{y_{j}^{k}}{2 k+1}-\frac{1}{2(2 k+1)} I_{\left\{y_{j}^{k}>0\right\}}
$$

as the estimator of $f_{j} \log f_{j}$ based on $y_{j}^{k}$.
To finish the derivation we decompose $\hat{f}_{j} \log f_{j}$ into two parts:

$$
\hat{f}_{j} \log f_{j}=\sum_{m=-k}^{k} w_{m} y_{j+m} \log f_{j}+\left(\hat{f}_{j}-\sum_{m=-k}^{k} w_{m} y_{j+m}\right) \log f_{j}
$$

Since the expectation of the first part is approximately $f_{j} \log f_{j} \sum_{m=-k}^{k} w_{m}$, we estimate it by $\beta_{j}^{k} \sum_{m=-k}^{k} w_{m}$. Notice also that the first term of the second part and $y_{j}^{k}$ are independent. Thus an approximately unbiased estimator of the second part is $\left(\hat{f}_{j}-\sum_{m=-k}^{k} w_{m} y_{j+m}\right) \alpha_{j}^{k}$. The parameter $k$, in a way, can be treated as a device for controlling the bias and variance of our estimator for $\hat{f}_{j} \log f_{j}$.

Finally, putting the two parts together we have

$$
\hat{f}_{j} \log f_{j} \approx \beta_{j}^{k} \sum_{m=-k}^{k} w_{m}+\left(\hat{f}_{j}-\sum_{m=-k}^{k} w_{m} y_{j+m}\right) \alpha_{j}^{k}
$$

This finishes the construction of $\hat{\Delta}_{\mathrm{KL}}^{k}(h)$, which is an approximately unbiased estimator of $\Delta_{\mathrm{KL}}(\hat{f}, f)$.

## Appendix C. Proof of Theorem 1

We first state and prove the following lemma. Let $Y$ denote a Poisson $(\lambda)$ random variable, and define residuals

$$
\begin{aligned}
r_{1}(\lambda)= & E\left[\left\{\log Y+\frac{0.5}{Y}-\frac{1.36177}{Y^{2}}+\frac{2.15204}{Y^{3}}\right\} I_{\{Y>0\}}-2.10898 I_{\{Y=0\}}\right] \\
& -\log \lambda, \\
r_{2}(\lambda)= & E\left(Y \log Y-\frac{1}{2} I_{\{Y>0\}}\right)-\lambda \log \lambda .
\end{aligned}
$$

Lemma C.1. The following relations are true:

$$
\begin{equation*}
E\left(\alpha_{j}^{k}\right)=\log \frac{f_{j}^{k}}{2 k+1}+r_{1}\left(f_{j}^{k}\right) \tag{21}
\end{equation*}
$$

$$
\begin{equation*}
E\left(\beta_{j}^{k}\right)=\frac{f_{j}^{k}}{2 k+1} \log \frac{f_{j}^{k}}{2 k+1}+\frac{r_{2}\left(f_{j}^{k}\right)}{2 k+1} \tag{22}
\end{equation*}
$$

Furthermore, as $\lambda \rightarrow \infty$ :

$$
\begin{align*}
& r_{1}(\lambda)=\mathrm{O}\left(1 / \lambda^{2}\right)  \tag{23}\\
& r_{2}(\lambda)=\mathrm{O}(1 / \lambda) \tag{24}
\end{align*}
$$

Proofs of (21) and (22). Notice that $y_{j}^{k}$ has a Poisson $\left(f_{j}^{k}\right)$ distribution and direct calculation shows

$$
E\left(\beta_{j}^{k}-\frac{f_{j}^{k}}{2 k+1} \log \frac{f_{j}^{k}}{2 k+1}\right)=\frac{1}{2 k+1} E\left(y_{j}^{k} \log y_{j}^{k}-f_{j}^{k} \log f_{j}^{k}-\frac{1}{2} I_{\left\{y_{j}^{k}>0\right\}}\right)
$$

Relation (22) follows immediately. Similarly one obtains

$$
\begin{aligned}
E & \left(\alpha_{j}^{k}-\log \frac{f_{j}^{k}}{2 k+1}\right) \\
& =E\left[\left\{\log y_{j}^{k}+\frac{0.5}{y_{j}^{k}}-\frac{1.36177}{\left(y_{j}^{k}\right)^{2}}+\frac{2.15204}{\left(y_{j}^{k}\right)^{3}}\right\} I_{\{Y>0\}}-2.10898 I_{\{Y=0\}}\right] \\
& \quad-\log \left(f_{j}^{k}\right)
\end{aligned}
$$

which implies (21).
Proof of (24). We first derive an upper bound for $r_{2}(\lambda)$. Using $\log y=\log \lambda+\log \{1+(y-$ $\lambda) / \lambda\}$ and $\log (1+y) \leqslant y-y^{2} / 2+y^{3} / 3$ we get

$$
\begin{aligned}
E(Y \log Y) & =E(Y \log \lambda)+E\left\{Y \log \left(1+\frac{Y-\lambda}{\lambda}\right)\right\} \\
& \leqslant \lambda \log \lambda+E\left[Y\left\{\frac{Y-\lambda}{\lambda}-\frac{1}{2}\left(\frac{Y-\lambda}{\lambda}\right)^{2}+\frac{1}{3}\left(\frac{Y-\lambda}{\lambda}\right)^{3}\right\}\right] \\
& =\lambda \log \lambda+\frac{1}{2}+\frac{5}{6 \lambda}+\frac{1}{3 \lambda^{2}}
\end{aligned}
$$

whence

$$
r_{2}(\lambda) \leqslant \frac{5}{6 \lambda}+\frac{1}{3 \lambda^{2}}+\frac{1}{2} \mathrm{e}^{-\lambda}
$$

Now we establish a lower bound for $r_{2}(\lambda)$, and we need two inequalities to proceed. The first inequality is, if $C>0$ then $\log (1+y) \geqslant y-y^{2} / 2+y^{3} / 3-(1+C) y^{4} / 4$ for $y>-D$, where $D>0$ depends on $C$. The second inequality is a classical large deviation result, namely, $P[(Y-\lambda) / \lambda \leqslant-D] \leqslant \mathrm{e}^{-K \lambda}$, where $K$ depends on $D$ (e.g., see Grimmett and Stirzaker,

2001, p. 202). With these two inequalities, we proceed as

$$
\begin{aligned}
E(Y \log Y)= & E(Y \log \lambda)+E\left\{Y \log \left(1+\frac{Y-\lambda}{\lambda}\right) I_{\{Y>\lambda-D \lambda\}}\right\} \\
& -E\left\{Y \log \left(1+\frac{Y-\lambda}{\lambda}\right) I_{\{Y \leqslant \lambda-D \lambda\}}\right\} \\
\geqslant & \lambda \log \lambda+E\left\{Y \log \left(1+\frac{Y-\lambda}{\lambda}\right) I_{\{Y>\lambda-D \lambda\}}\right\} \\
& +\min _{0 \leqslant x \leqslant \lambda-D \lambda}\left\{x \log \left(1+\frac{x-\lambda}{\lambda}\right)\right\} P\left(\frac{Y-\lambda}{\lambda} \leqslant-D\right) \\
\geqslant & E\left[Y \left\{\frac{Y-\lambda}{\lambda}-\frac{1}{2}\left(\frac{Y-\lambda}{\lambda}\right)^{2}\right.\right. \\
& \left.\left.+\frac{1}{3}\left(\frac{Y-\lambda}{\lambda}\right)^{3}-\frac{1+C}{4}\left(\frac{Y-\lambda}{\lambda}\right)^{4}\right\}\right] \\
& +\lambda \log \lambda-\lambda \mathrm{e}^{-K \lambda-1} \\
= & \lambda \log \lambda+\frac{1}{2}+\frac{1}{\lambda}\left(\frac{1}{12}-\frac{3 C}{4}\right)+\mathrm{O}\left(\frac{1}{\lambda^{2}}\right)
\end{aligned}
$$

and Eq. (24) follows.
Proof of (23). Using similar arguments as above we conclude that

$$
E\left(\log Y I_{\{Y>0\}}\right)=\log \lambda-\frac{1}{2 \lambda}+\mathrm{O}\left(\frac{1}{\lambda^{2}}\right) .
$$

Analogously we can write $x^{-1}=\lambda^{-1}\{1+(x-\lambda) / \lambda\}^{-1}$. It is again well-known that $1 /(1+$ $y) \geqslant 1-y$ and if $C>0$ than $1 /(1+y) \leqslant 1-y+(1+c) y^{2}$ for $y>-D$, where $D>0$ depends on $C$. From here

$$
E\left(\frac{1}{Y} I_{\{Y>0\}}\right) \geqslant \frac{1}{\lambda} E\left(1-\frac{Y-\lambda}{\lambda}\right) I_{\{Y>0\}}=\frac{1}{\lambda}-\frac{2}{\lambda} \mathrm{e}^{-\lambda}
$$

and

$$
\begin{aligned}
E\left(\frac{1}{Y} I_{\{Y>0\}}\right) \leqslant & \frac{1}{\lambda} E\left(\frac{1}{1+(Y-\lambda) / \lambda} I_{\{Y>\lambda-D \lambda\}}\right) \\
& +\max _{1 \leqslant x \leqslant \lambda-D \lambda} \frac{1}{x} P(1 \leqslant Y \leqslant \lambda-D \lambda) \\
\leqslant & \frac{1}{\lambda}+\frac{1+C}{\lambda^{2}}+\mathrm{e}^{-K \lambda} .
\end{aligned}
$$

Similar considerations show that

$$
E\left(\frac{1}{Y^{k}}\right)=\frac{1}{\lambda^{k}}+\mathrm{O}\left(\frac{1}{\lambda^{k+1}}\right)
$$

and Relation (23) follows by simple algebra. This completes proving Lemma C. 1 and we are now ready to give the proof for Theorem 1.

Proof of (7). To compute the bias consider $\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)=n^{-1} \sum_{j=0}^{n-1} S_{j}$ and decompose each summand $S_{j}$ into four parts:

$$
\begin{align*}
S_{j}= & \left(y_{j}-f_{j}\right)-\left(\alpha_{j}^{k}-\log f_{j}\right) \sum_{|m| \geqslant k} w_{m} y_{j+m} \\
& -\left(\beta_{j}^{k}-f_{j} \log f_{j}\right) \sum_{|m| \leqslant k} w_{m}+\sum_{|m| \leqslant k} w_{m}\left(y_{j+m}-f_{j}\right) \log f_{j} . \tag{25}
\end{align*}
$$

Let us calculate $E\left(S_{j}\right)$ term by term:

$$
\begin{align*}
& E\left(y_{j}-f_{j}\right)=0,  \tag{26}\\
& E\left\{\begin{array}{l}
\left.\left(\alpha_{j}^{k}-\log f_{j}\right) \sum_{|m| \geqslant k} w_{m} y_{j+m}\right\} \\
\\
=\left\{r_{1}\left(f_{j}^{k}\right)-\log \frac{f_{j}}{f_{j}^{k} /(2 k+1)}\right\} \sum_{|m| \geqslant k} w_{m} f_{j+m}, \\
E\left\{\left(\beta_{j}^{k}-f_{j} \log f_{j}\right) \sum_{|m| \leqslant k} w_{m}\right\} \\
\\
=r_{2}\left(f_{j}^{k}\right) \frac{1}{2 k+1} \sum_{|m| \leqslant k} w_{m}+\left(\frac{f_{j}^{k}}{2 k+1} \log \frac{f_{j}^{k}}{2 k+1}-f_{j} \log f_{j}\right) \sum_{|m| \leqslant k} w_{m}, \\
E\left\{\sum_{|m| \leqslant k} w_{m} \log f_{j}\left(y_{j+m}-f_{j}\right)\right\}=\sum_{|m| \leqslant k} w_{m}\left(f_{j+m}-f_{j}\right) \log f_{j} .
\end{array}\right.
\end{align*}
$$

Recall $M_{1}=\max f$ and $M_{2}=\min f$. Combining Eqs. (26)-(29), observing the fact $\sum_{|m| \leqslant k} w_{m} \leqslant(2 k+1) w_{0}$, and using inequalities

$$
\left|\log \frac{y}{x}\right| \leqslant \frac{|x-y|}{y} \quad \text { and } \quad|x \log x-y \log y| \leqslant|x-y||1+\log y|+\frac{|x-y|^{2}}{2 y}
$$

we get

$$
\begin{aligned}
\left|E\left(S_{j}\right)\right| \leqslant & M_{1} r_{1}\left(f_{j}^{k}\right)+w_{0} r_{2}\left(f_{j}^{k}\right)+\frac{M_{1}}{M_{2}}\left|\frac{f_{j}^{k}}{2 k+1}-f_{j}\right| \\
& +\left|\frac{f_{j}^{k}}{2 k+1}-f_{j}\right|\left\{1+\max \left(\log M_{1},-\log M_{2}\right)\right\}(2 k+1) w_{0} \\
& +\frac{1}{2 M_{2}}\left|\frac{f_{j}^{k}}{2 k+1}-f_{j}\right|^{2}(2 k+1) w_{0} \\
& +\max \left(\log M_{1},-\log M_{2}\right) w_{0} \sum_{|m| \leqslant k}\left|f_{j+m}-f_{j}\right| .
\end{aligned}
$$

Observe that $f_{j}^{k} \geqslant M_{2}(2 k+1)$, and $w_{0} \leqslant K^{\prime} / b$, where $K^{\prime}$ is a constant depending only on the kernel $K$. Combining these observations with Lemma C. 1 and the fact that $f$ is Lipschitz with constant $D$ one obtains (7).

Proof of (8). By noting that the $w_{m}$ 's are zero when $|m|>b_{n} / 2$, and that the observations are independent, we have

$$
\begin{align*}
\operatorname{var}\left\{\hat{\Lambda}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)\right\} & =\frac{1}{n^{2}} \sum_{i=0}^{n-1} \sum_{i=0}^{n-1} \operatorname{cov}\left(S_{i}, S_{j}\right)=\frac{1}{n^{2}} \sum_{|i-j| \leqslant b} \operatorname{cov}\left(S_{i}, S_{j}\right) \\
& \leqslant \frac{1}{n^{2}} \sum_{|i-j| \leqslant b}\left\{\operatorname{var}\left(S_{i}\right) \operatorname{var}\left(S_{j}\right)\right\}^{1 / 2} \tag{30}
\end{align*}
$$

Therefore we need to prove that $\operatorname{var}\left(S_{i}\right)$ is bounded. Using Eq. (25) we get

$$
\begin{align*}
& \operatorname{var}\left(S_{j}\right) \leqslant 4 \operatorname{var}\left(y_{j}\right)+4 \operatorname{var}\left\{\left(\alpha_{j}^{k}-\log f_{j}\right) \sum_{|m| \geqslant k} w_{m} y_{j+m}\right\} \\
&+4\left(\sum_{|m| \leqslant k} w_{m}\right)^{2} \operatorname{var}\left(\beta_{j}^{k}\right)+4\left(\log f_{j}\right)^{2} \operatorname{var}\left(\sum_{|m| \leqslant k} w_{m} y_{j+m}\right) \tag{31}
\end{align*}
$$

Notice that the large deviations considerations mentioned before give us that

$$
P\left(M_{2}-\varepsilon<y_{j}^{k}<M_{1}+\varepsilon\right) \geqslant 1-\mathrm{e}^{-c k} \quad \text { for } M_{2}>\varepsilon>0 \text { and some } c>0
$$

This combined with the definition of $\alpha_{j}^{k}, \beta_{j}^{k}$ and the fact that $y_{j}^{k}$ has a Poisson distribution immediately imply that both $\operatorname{var}\left(\beta_{j}^{k}\right)$ and $\operatorname{var}\left(\alpha_{j}^{k}\right)$ are bounded by a constant $\tilde{C}$ that depends on $M_{1}$ and $M_{2}$.

Let us now calculate each part of (31) separately:

$$
\begin{align*}
& \operatorname{var}\left(y_{j}\right) \leqslant M_{1}  \tag{32}\\
& \left(\sum_{|m| \leqslant k} w_{m}\right)^{2} \operatorname{var}\left(\beta_{j}^{k}\right) \leqslant C_{3}^{\prime}\left(\frac{k}{b}\right)^{2},  \tag{33}\\
& \left(\log f_{j}\right)^{2} \operatorname{var}\left(\sum_{|m| \leqslant k} w_{m} y_{j+m}\right) \leqslant C_{4}^{\prime} \frac{2 k+1}{b^{2}} M_{1} \max \left(-\log M_{2}, \log M_{1}\right)^{2} . \tag{34}
\end{align*}
$$

The only part that requires a little bit more attention is:

$$
\begin{align*}
\operatorname{var} & \left\{\left(\alpha_{j}^{k}-\log f_{j}\right) \sum_{|m| \geqslant k} w_{m} y_{j+m}\right\} \\
= & E\left\{\left(\sum_{|m| \geqslant k} w_{m} y_{j+m}\right)^{2}\right\} \operatorname{var}\left(\alpha_{j}^{k}\right) \\
& +\operatorname{var}\left(\sum_{|m| \geqslant k} w_{m} y_{j+m}\right)\left\{E\left(\alpha_{j}^{k}-\log f_{j}\right)\right\}^{2} \\
\leqslant & \left(M_{1}^{2}+M_{1} \sum_{k} w_{m}^{2}\right) \tilde{C}+M_{1}\left(\sum_{k} w_{m}^{2}\right) \\
& \times\left[\log \left\{\frac{f_{j}^{k} /(2 k+1)}{f_{j}}\right\}+r_{1}\left(f_{j}^{k}\right)\right]^{2} \tag{35}
\end{align*}
$$

Now by substituting (32)-(35) into (31) one can see that there is a universal constant $C$ depending on the function $f$ through $M_{1}, M_{2}$ and the Lipschitz constant $D$ such that $\operatorname{var}\left(S_{j}\right) \leqslant C$. Therefore from (30) we arrive (8).

Proof of (9). We will need to use the following relations:

$$
\begin{align*}
& E\left(\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)\right)^{2}=\mathrm{O}\left(\frac{b_{n}}{n}+\frac{1}{k^{4}}\right),  \tag{36}\\
& \operatorname{var} \Delta_{\mathrm{KL}}(\hat{f}, f)=\mathrm{O}\left(\frac{b_{n}}{n}\right)  \tag{37}\\
& E\left\{\Delta_{\mathrm{KL}}(\hat{f}, f)\right\} \geqslant \frac{C}{b_{n}}+\mathrm{o}\left(\frac{1}{b_{n}}\right) . \tag{38}
\end{align*}
$$

Recall, $b_{n}=\mathrm{o}\left\{\min \left(n^{1 / 3}, k_{n}^{2}\right)\right\}$. Thus both $\left(b_{n} / n\right)^{1 / 2}=\mathrm{o}\left(1 / b_{n}\right), 1 / k_{n}^{2}=\mathrm{o}\left(1 / b_{n}\right)$ and there is $r_{n}$ such that $r_{n}=\mathrm{o}\left(1 / b_{n}\right)$ and $b_{n} / n+1 / k^{4}=\mathrm{o}\left(r_{n}^{2}\right)$. Fix $\varepsilon>0$ and calculate:

$$
\begin{aligned}
P\left(\left|\frac{\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)}{\Delta_{\mathrm{KL}}(\hat{f}, f)}\right|>\varepsilon\right)< & P\left(\left|\frac{\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)}{r_{n}}\right|>\varepsilon\right) \\
& +P\left(\Delta_{\mathrm{KL}}(\hat{f}, f)<r_{n}\right)
\end{aligned}
$$

By combining (36), (38), (37), the Markov's and Chebyshev's inequalities we get

$$
\begin{gathered}
P\left(\left|\frac{\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)}{r_{n}}\right|>\varepsilon\right)<\frac{E\left(\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)\right)^{2}}{\varepsilon^{2} r_{n}^{2}} \rightarrow 0, \\
P\left(\Delta_{\mathrm{KL}}(\hat{f}, f)<r_{n}\right)<P\left(\left|\Delta_{\mathrm{KL}}(\hat{f}, f)-E \Delta_{\mathrm{KL}}(\hat{f}, f)\right|>E \Delta_{\mathrm{KL}}(\hat{f}, f)-r_{n}\right) \\
<\frac{\operatorname{var} \Delta_{\mathrm{KL}}(\hat{f}, f)}{\left(E \Delta_{\mathrm{KL}}(\hat{f}, f)-r_{n}\right)^{2}} \rightarrow 0 .
\end{gathered}
$$

This proves (9). The only remaining part is to verify (36), (38) and (37).

## Proof of (36). Recall

$$
\begin{aligned}
E\left(\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)\right)^{2}= & \operatorname{var} E\left(\hat{\Delta}_{\mathrm{KL}}^{k}(h)-\Delta_{\mathrm{KL}}(\hat{f}, f)\right)^{2} \\
& +\left(E \hat{\Delta}_{\mathrm{KL}}^{k}(h)-E \Delta_{\mathrm{KL}}(\hat{f}, f)\right)^{2} .
\end{aligned}
$$

Since $k_{n}<b_{n}<n$ the right-hand side of (7) is of the order $1 / k^{2}+k / n$. Thus Eqs. (7) and (8) imply (36).

Proof of (37). The proof follows along the same steps as proof of (8) and we omit the details.

Proof of (38). We need two inequalities to prove (38). Define $l(y)=(y-1)-\log (y)$ and hence $\Delta_{\mathrm{KL}}(\hat{f}, f)=n^{-1} \sum_{j=0}^{n-1} f_{j} l\left(\hat{f}_{j} / f_{j}\right)$. By applying the Taylor approximation $l(y) \approx$ $\frac{1}{2}(y-1)^{2}$ to $l\left(\hat{f}_{j} / f_{j}\right)$ and using the assumption that $f$ is bounded away from 0 and $\infty$, we obtain our first inequality:

$$
\begin{equation*}
C \frac{\left(\hat{f}_{j}-f_{j}\right)^{2}}{f_{j}} \leqslant f_{j} l\left(\frac{\hat{f}_{j}}{f_{j}}\right) \quad \text { with } C=\frac{1}{2} \frac{\min \left(f_{j}\right)}{\max \left(f_{j}\right)} \tag{39}
\end{equation*}
$$

To get the second inequality calculate

$$
\begin{equation*}
\frac{E\left(\hat{f}_{j}-f_{j}\right)^{2}}{f_{j}}=2 f_{j}-2 E\left(\hat{f}_{j}\right)+\frac{E\left(\hat{f}_{j}^{2}\right)-f_{j}^{2}}{f_{j}} \tag{40}
\end{equation*}
$$

Notice that

$$
\begin{equation*}
E\left(\hat{f}_{j}^{2}\right)=\left\{E\left(\hat{f}_{j}\right)\right\}^{2}+\sum_{m} w_{m}^{2} f_{j+m} \tag{41}
\end{equation*}
$$

Thus combining (40) and (41) we get

$$
\frac{1}{n} \sum_{j} \frac{E\left(\hat{f}_{j}-f_{j}\right)^{2}}{f_{j}}=\frac{1}{n} \sum_{j}\left[\frac{f_{j}+E\left(\hat{f}_{j}\right)}{f_{j}}\left\{E\left(\hat{f}_{j}\right)-f_{j}\right\}+\sum_{m} w_{m}^{2} \frac{f_{j+m}}{f_{j}}\right] .
$$

Since the weights $w_{m}$ 's are zero when $|m|>b_{n} / 2$ and the function $f$ is Lipschitz, we have

$$
\begin{equation*}
\left\{E\left(\hat{f}_{j}\right)-f_{j}\right\}=\sum_{m=-n}^{2 n-1} w_{m-j}\left\{E\left(y_{m}\right)-f_{j}\right\} \leqslant D \frac{b_{n}}{n} \tag{42}
\end{equation*}
$$

Also notice that

$$
\begin{equation*}
\sum_{m=-n}^{2 n-1} w_{m-j}^{2} \approx \frac{L \int K^{2}(\omega) \mathrm{d} \omega}{b_{n}}, \tag{43}
\end{equation*}
$$

where $L$ is the length of the support of $K$. Combining Eqs. (40)-(43) we can conclude that there is a constant $D_{1}>0$ depending on $K$ such that

$$
\frac{1}{n} \sum_{j} \frac{E\left(\hat{f}_{j}-f_{j}\right)^{2}}{f_{j}} \geqslant \frac{D_{1}}{b_{n}}+\mathrm{O}\left\{\frac{b_{n}}{n}\right\}
$$

Eq. (38) then follows from this and our first inequality (39).

## Appendix D. Proof of Theorem 2

Notice that $\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)=n^{-1} \sum_{j=0}^{n-1} Z_{j}$ where

$$
\begin{equation*}
Z_{j}=2 y_{j}\left(f_{j}-\hat{f}_{j}\right)+\left(y_{j}\right)^{2}-\left(f_{j}\right)^{2}+\left(2 w_{0}-1\right) y_{j} . \tag{44}
\end{equation*}
$$

Using independence of $y_{j}$ we get

$$
E\left(Z_{j}\right)=2 E\left\{y_{j} w_{0}\left(f_{j}-y_{j}\right)\right\}+f_{j}+\left(2 w_{0}-1\right) f_{j}=0
$$

proving (13).
Let us now turn our attention to the variance. Notice that $w_{m}$ 's are zero when $|m|>b_{n} / 2$, whence the independence of observations implies:

$$
\begin{align*}
\operatorname{var}\left\{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)\right\} & =\frac{1}{n^{2}} \sum_{i=0}^{n-1} \sum_{i=0}^{n-1} \operatorname{cov}\left(Z_{i}, Z_{j}\right)=\frac{1}{n^{2}} \sum_{|i-j| \leqslant b} \operatorname{cov}\left(Z_{i}, Z_{j}\right) \\
& \leqslant \frac{1}{n^{2}} \sum_{|i-j| \leqslant b}\left\{\operatorname{var}\left(Z_{i}\right) \operatorname{var}\left(Z_{j}\right)\right\}^{1 / 2} . \tag{45}
\end{align*}
$$

Therefore we need to prove that $\operatorname{var}\left(Z_{i}\right)$ is bounded. Using Eq. (44) we get

$$
\operatorname{var}\left(Z_{j}\right) \leqslant 3 \operatorname{var}\left\{2 y_{j}\left(f_{j}-\hat{f}_{j}\right)\right\}+3 \operatorname{var}\left\{\left(y_{j}\right)^{2}\right\}+3 \operatorname{var}\left\{\left(2 w_{0}-1\right) y_{j}\right\}
$$

Since the function $f$ is bounded and if $Y$ has $\operatorname{Poisson}(\lambda)$ distribution then $E\left(Y^{4}\right)=\lambda+$ $7 \lambda^{2}+6 \lambda^{3}+\lambda^{4}$ we conclude that there is a universal constant $C$ depending on the function $f$ through max $f$, such that $\operatorname{var}\left(Z_{j}\right) \leqslant C$. This and the fact that (45) has no more than $(2 b+1) n$ non-zero terms implies

$$
\operatorname{var}\left\{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)\right\} \leqslant C \frac{b}{n}
$$

which is (14).
Finally, we will prove (15). Notice first that arguments almost identical to those in the proof of (14) imply

$$
\begin{equation*}
\operatorname{var} \Delta_{\mathrm{R}}(\hat{f}, f) \leqslant C^{\prime} \frac{b}{n} \tag{46}
\end{equation*}
$$

Second, we will estimate $E \Delta_{\mathrm{R}}(\hat{f}, f)$. Substituting

$$
\begin{equation*}
E\left(\hat{f}_{j}^{2}\right)=\left\{E\left(\hat{f}_{j}\right)\right\}^{2}+\sum_{m} w_{m}^{2} f_{j+m} \tag{47}
\end{equation*}
$$

into

$$
\begin{equation*}
E\left\{\left(\hat{f}_{j}-f_{j}\right)^{2}\right\}=\left(f_{j}\right)^{2}-2 f_{j} E\left(\hat{f}_{j}\right)+E\left(\hat{f}_{j}^{2}\right) \tag{48}
\end{equation*}
$$

we get

$$
\frac{1}{n} \sum_{j} E\left(\hat{f}_{j}-f_{j}\right)^{2}=\frac{1}{n} \sum_{j}\left[\left\{f_{j}-E\left(\hat{f}_{j}\right)\right\}^{2}+\sum_{m} w_{m}^{2} f_{j+m}\right] .
$$

The assumption that function $f$ is Lipschitz assures that $\left|f_{m}-f_{j}\right|<D|m-j| / n$. Since the weights $w_{m}$ 's are zero when $|m|>b_{n} / 2$, we have

$$
\begin{equation*}
\left\{E\left(\hat{f}_{j}\right)-f_{j}\right\}^{2}=\left\{\sum_{m=-n}^{2 n-1} w_{m-j}\left(f_{m}-f_{j}\right)\right\}^{2} \leqslant\left(D \frac{b_{n}}{n}\right)^{2} \tag{49}
\end{equation*}
$$

Combining Eqs. (43) and (48) we can conclude that there is a constant $D_{2}>0$ depending on $K$ and $M$, such that

$$
\begin{equation*}
\frac{1}{n} \sum_{j} E\left\{\left(\hat{f}_{j}-f_{j}\right)^{2}\right\} \geqslant \frac{D_{2}}{b_{n}}+\mathrm{O}\left[\left\{\frac{b_{n}}{n}\right\}^{2}\right] \tag{50}
\end{equation*}
$$

Recall, $b_{n}=\mathrm{o}\left(n^{1 / 3}\right)$. Thus $\left(b_{n} / n\right)^{1 / 2}=\mathrm{o}\left(1 / b_{n}\right)$ and there is $r_{n}$ such that $r_{n}=\mathrm{o}\left(1 / b_{n}\right)$ and $\left(b_{n} / n\right)^{1 / 2}=\mathrm{o}\left(r_{n}\right)$. Fix $\varepsilon>0$ and calculate:

$$
\begin{aligned}
P\left(\left|\frac{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)}{\Delta_{\mathrm{R}}(\hat{f}, f)}\right|>\varepsilon\right)< & P\left(\left|\frac{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)}{r_{n}}\right|>\varepsilon\right) \\
& +P\left(\Delta_{\mathrm{R}}(\hat{f}, f)<r_{n}\right) .
\end{aligned}
$$

By combining (13), (14), (46), (50), and the Chebyshev's inequality we get

$$
\begin{aligned}
& P\left(\left|\frac{\hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)}{r_{n}}\right|>\varepsilon\right)<\frac{\operatorname{var} \hat{\Delta}_{\mathrm{R}}(h)-\Delta_{\mathrm{R}}(\hat{f}, f)}{\varepsilon^{2} r_{n}^{2}}<\frac{C b_{n} / n}{\varepsilon^{2} r_{n}^{2}} \rightarrow 0, \\
& P\left(\Delta_{\mathrm{R}}(\hat{f}, f)<r_{n}\right)<P\left(\left|\Delta_{\mathrm{R}}(\hat{f}, f)-E \Delta_{\mathrm{R}}(\hat{f}, f)\right|>E \Delta_{\mathrm{R}}(\hat{f}, f)-r_{n}\right) \\
& \quad<\frac{\operatorname{var} \Delta_{\mathrm{R}}(\hat{f}, f)}{\left(E \Delta_{\mathrm{R}}(\hat{f}, f)-r_{n}\right)^{2}}<\frac{C^{\prime} b_{n} / n}{\left(D_{2} / b_{n}-D\left(b_{n} / n\right)^{2}-r_{n}\right)^{2}} \rightarrow 0 .
\end{aligned}
$$

This proves (15).

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